## Research Article

# Some Similarity between Contractions and Kannan Mappings 

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Contractions are always continuous and Kannan mappings are not necessarily continuous. This is a very big difference between both mappings. However, we know that relaxed both mappings are quite similar. In this paper, we discuss both mappings from a new point of view.

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## 1. Introduction

Let $(X, d)$ be a metric space and let $T$ be a mapping on $X$. Then $T$ is called a contraction if there exists $r \in[0,1)$ such that

$$
\begin{equation*}
d(T x, T y) \leq r d(x, y) \tag{1.1}
\end{equation*}
$$

for all $x, y \in X . T$ is called Kannan if there exists $\alpha \in[0,1 / 2)$ such that

$$
\begin{equation*}
d(T x, T y) \leq \alpha d(x, T x)+\alpha d(y, T y) \tag{1.2}
\end{equation*}
$$

for all $x, y \in X$. We know that if $X$ is complete, then every contraction and every Kannan mapping have a unique fixed point, see [1, 2]. We know that both conditions are independent, that is, there exist a contraction, which is not Kannan, and a Kannan mapping, which is not a contraction. Thus we cannot compare both conditions directly. So we compare both indirectly.

## Fact 1

Banach fixed-point theorem, which is often called the Banach contraction principle, is very important because it is a very forceful tool in nonlinear analysis. We think that Kannan fixed-point theorem is also very important because Subrahmanyam [3] proved that Kannan theorem characterizes the metric completeness of underlying spaces, that is, a metric space $X$ is complete if and only if every Kannan mapping on $X$ has a fixed point. On the other hand, Connell [4] gave an example of a metric space $X$ such that $X$ is not complete and every contraction on $X$ has a fixed point. Thus the Banach theorem cannot characterize the metric completeness of $X$. Therefore, we consider that the notion of contractions is stronger from this point of view.

## Fact 2

Using the notion of $\tau$-distances, Suzuki [5] considered some weaker contractions and Kannan mappings and proved the following.
(i) If $T$ is a contraction with respect to a $\tau$-distance, then $T$ is Kannan with respect to another $\tau$-distance.
(ii) If $T$ is Kannan with respect to a $\tau$-distance, then $T$ is a contraction with respect to another $\tau$-distance.

That is, both conditions are completely the same.
Recently, Suzuki [6] proved the following theorem, see also [7].
Theorem 1.1 (see [6]). Define a nonincreasing function $\theta$ from $[0,1)$ onto $(1 / 2,1]$ by

$$
\theta(r)= \begin{cases}1 & \text { if } 0 \leq r \leq \frac{1}{2}(\sqrt{5}-1)  \tag{1.3}\\ \frac{1-r}{r^{2}} & \text { if } \frac{1}{2}(\sqrt{5}-1) \leq r \leq \frac{1}{\sqrt{2}} \\ \frac{1}{1+r} & \text { if } \frac{1}{\sqrt{2}} \leq r<1\end{cases}
$$

Then for a metric space $(X, d)$, the following are equivalent:
(i) X is complete,
(ii) every mapping $T$ on $X$, satisfying the following, has a fixed point: there exists $r \in[0,1)$ such that $\theta(r) d(x, T x) \leq d(x, y)$ implies $d(T x, T y) \leq r d(x, y)$ for all $x, y \in X$.
Remark 1.2. $\theta(r)$ is the best constant for every $r$.
The purpose of this paper is to prove a Kannan version of Theorem 1.1. Then we compare the theorem (Theorem 2.2) with Theorem 1.1 and attempt to judge which is stronger from our new point of view.

## 2. Kannan mappings

Throughout this paper we denote by $\mathbb{N}$ the set of all positive integers and by $\mathbb{R}$ the set of all real numbers.

In this section, we prove our main result. We begin with the following lemma.

Lemma 2.1. Let $(X, d)$ be a metric space and let $T$ be a mapping on $X$. Let $x \in X$ satisfy $d\left(T x, T^{2} x\right) \leq$ $r d(x, T x)$ for some $r \in[0,1)$. Then for $y \in X$, either

$$
\begin{equation*}
\frac{1}{1+r} d(x, T x) \leq d(x, y) \quad \text { or } \quad \frac{1}{1+r} d\left(T x, T^{2} x\right) \leq d(T x, y) \tag{2.1}
\end{equation*}
$$

holds.
Proof. We assume

$$
\begin{equation*}
\frac{1}{1+r} d(x, T x)>d(x, y), \quad \frac{1}{1+r} d\left(T x, T^{2} x\right)>d(T x, y) \tag{2.2}
\end{equation*}
$$

Then we have

$$
\begin{align*}
d(x, T x) & \leq d(x, y)+d(y, T x) \\
& <\frac{1}{1+r}\left(d(x, T x)+d\left(T x, T^{2} x\right)\right)  \tag{2.3}\\
& \leq \frac{1}{1+r}(d(x, T x)+r d(x, T x))=d(x, T x)
\end{align*}
$$

This is a contradiction.
The following theorem is a Kannan version of Theorem 1.1.
Theorem 2.2. Define a nonincreasing function $\varphi$ from $[0,1)$ into $(1 / 2,1]$ by

$$
\varphi(r)= \begin{cases}1 & \text { if } 0 \leq r<\frac{1}{\sqrt{2}}  \tag{2.4}\\ \frac{1}{1+r} & \text { if } \frac{1}{\sqrt{2}} \leq r<1\end{cases}
$$

Let $(X, d)$ be a complete metric space and let $T$ be a mapping on $X$. Let $\alpha \in[0,1 / 2)$ and put $r:=$ $\alpha /(1-\alpha) \in[0,1)$. Assume that

$$
\begin{equation*}
\varphi(r) d(x, T x) \leq d(x, y) \quad \text { implies } d(T x, T y) \leq \alpha d(x, T x)+\alpha d(y, T y) \tag{2.5}
\end{equation*}
$$

for all $x, y \in X$, then $T$ has a unique fixed point $z$ and $\lim _{n} T^{n} x=z$ holds for every $x \in X$.
Proof. Since $\varphi(r) \leq 1, \varphi(r) d(x, T x) \leq d(x, T x)$ holds. From the assumption, we have

$$
\begin{equation*}
d\left(T x, T^{2} x\right) \leq \alpha d(x, T x)+\alpha d\left(T x, T^{2} x\right) \tag{2.6}
\end{equation*}
$$

and hence

$$
\begin{equation*}
d\left(T x, T^{2} x\right) \leq r d(x, T x) \tag{2.7}
\end{equation*}
$$

for $x \in X$. Let $u \in X$. Put $u_{0}=u$ and $u_{n}=T^{n} u$ for all $n \in \mathbb{N}$. From (2.7), we have

$$
\begin{equation*}
\sum_{n=1}^{\infty} d\left(u_{n}, u_{n+1}\right) \leq \sum_{n=1}^{\infty} r^{n} d\left(u_{0}, u_{1}\right)<\infty \tag{2.8}
\end{equation*}
$$



Figure 1

So $\left\{u_{n}\right\}$ is a Cauchy sequence in $X$ and by the completeness of $X$, there exists a point $z$ such that $u_{n} \rightarrow z$.

We next show

$$
\begin{equation*}
d(z, T x) \leq \alpha d(x, T x), \quad \forall x \in X \text { with } x \neq z . \tag{2.9}
\end{equation*}
$$

Since $u_{n} \rightarrow z$, there exists $n_{0} \in \mathbb{N}$ such that $d\left(u_{n}, z\right) \leq(1 / 3) d(x, z)$ for all $n \in \mathbb{N}$ with $n \geq n_{0}$. Then we have

$$
\begin{align*}
\varphi(r) d\left(u_{n}, T u_{n}\right) & \leq d\left(u_{n}, T u_{n}\right)=d\left(u_{n}, u_{n+1}\right) \\
& \leq d\left(u_{n}, z\right)+d\left(u_{n+1}, z\right) \\
& \leq \frac{2}{3} d(x, z)=d(x, z)-\frac{1}{3} d(x, z)  \tag{2.10}\\
& \leq d(x, z)-d\left(u_{n}, z\right) \leq d\left(u_{n}, x\right)
\end{align*}
$$

and hence

$$
\begin{equation*}
d\left(T u_{n}, T x\right) \leq \alpha d\left(u_{n}, T u_{n}\right)+\alpha d(x, T x) \quad \text { for } n \in \mathbb{N} \text { with } n \geq n_{0} . \tag{2.11}
\end{equation*}
$$

Therefore, we obtain

$$
\begin{align*}
d(z, T x) & =\lim _{n \rightarrow \infty} d\left(u_{n+1}, T x\right)=\lim _{n \rightarrow \infty} d\left(T u_{n}, T x\right) \\
& \leq \lim _{n \rightarrow \infty}\left(\alpha d\left(u_{n}, T u_{n}\right)+\alpha d(x, T x)\right)  \tag{2.12}\\
& =\alpha d(x, T x)
\end{align*}
$$

for $x \in X$ with $x \neq z$.
Let us prove that $z$ is a fixed point of $T$. In the case where $0 \leq r<1 / \sqrt{2}$, arguing by contradiction, we assume that $T z \neq z$. Then we have, from (2.9),

$$
\begin{equation*}
d\left(z, T^{2} z\right) \leq \alpha d\left(T z, T^{2} z\right) \leq \operatorname{\alpha rd}(z, T z) \tag{2.13}
\end{equation*}
$$

and hence

$$
\begin{align*}
d(z, T z) & \leq d\left(z, T^{2} z\right)+d\left(T z, T^{2} z\right) \\
& \leq \alpha r d(z, T z)+r d(z, T z)=\frac{r+2 r^{2}}{1+r} d(z, T z)  \tag{2.14}\\
& <\frac{r+1}{1+r} d(z, T z)=d(z, T z)
\end{align*}
$$

This is a contradiction. Therefore, we obtain $T z=z$. In the case where $1 / \sqrt{2} \leq r<1$, from Lemma 2.1, either

$$
\begin{equation*}
\varphi(r) d\left(u_{2 n}, u_{2 n+1}\right) \leq d\left(u_{2 n}, z\right) \quad \text { or } \quad \varphi(r) d\left(u_{2 n+1}, u_{2 n+2}\right) \leq d\left(u_{2 n+1}, z\right) \tag{2.15}
\end{equation*}
$$

holds for $n \in \mathbb{N}$. Thus there exists a subsequence $\left\{n_{j}\right\}$ of $\{n\}$ such that

$$
\begin{equation*}
\varphi(r) d\left(u_{n_{j}}, u_{n_{j}+1}\right) \leq d\left(u_{n_{j}}, z\right) \tag{2.16}
\end{equation*}
$$

for $j \in \mathbb{N}$. From the assumption, we have

$$
\begin{equation*}
d(z, T z)=\lim _{j \rightarrow \infty} d\left(u_{n_{j}+1}, T z\right) \leq \lim _{j \rightarrow \infty}\left(\alpha d\left(u_{n_{j}}, u_{n_{j}+1}\right)+\alpha d(z, T z)\right)=\alpha d(z, T z) . \tag{2.17}
\end{equation*}
$$

Since $\alpha<1 / 2$, we have $T z=z$. Therefore, we have shown $T z=z$ in both cases.
From (2.9), we obtain that the fixed point $z$ is unique.
Remark 2.3. Since $\theta(r) \leq \varphi(r)$ for every $r$, we can consider that Kannan is stronger from our new point of view. Though $\theta$ and $\varphi$ are different, we remark that the graphs of $\theta$ and $\varphi$ are quite similar.

The following theorem shows that $\varphi(r)$ is the best constant for every $r$.
Theorem 2.4. Define a function $\varphi$ as in Theorem 2.2. For every $\alpha \in[0,1 / 2)$, putting $r=\alpha /(1-\alpha)$, there exist a complete metric space $(X, d)$ and a mapping $T$ on $X$ such that $T$ has no fixed points and

$$
\begin{equation*}
\varphi(r) d(x, T x)<d(x, y) \quad \text { implies } d(T x, T y) \leq \alpha d(x, T x)+\alpha d(y, T y) \tag{2.18}
\end{equation*}
$$

for all $x, y \in X$.
Proof. In the case where $0 \leq r<1 / \sqrt{2}$, define a complete subset $X$ of the Euclidean space $\mathbb{R}$ by $X=\{-1,1\}$. We also define a mapping $T$ on $X$ by $T x=-x$ for $x \in X$. Then $T$ dose not have a fixed point and

$$
\begin{equation*}
\varphi(r) d(x, T x)=2 \geq d(x, y) \tag{2.19}
\end{equation*}
$$

for all $x, y \in X$. In the case where $1 / \sqrt{2} \leq r<1$, define a complete subset $X$ of the Euclidean space $\mathbb{R}$ by

$$
\begin{equation*}
X=\{0,1\} \cup\left\{x_{n}: n \in \mathbb{N} \cup\{0\}\right\} \tag{2.20}
\end{equation*}
$$

where $x_{n}=(1-r)(-r)^{n}$ for all $n \in \mathbb{N} \cup\{0\}$. Define a mapping $T$ on $X$ by $T 0=1, T 1=1-r$, and $T x_{n}=x_{n+1}$ for $n \in \mathbb{N} \cup\{0\}$. Then the following are obvious:
(i) $d(T 0, T 1)=r=\alpha d(0, T 0)+\alpha d(1, T 1)$,
(ii) $\varphi(r) d(0, T 0) \geq \varphi(r) d\left(x_{n}, T x_{n}\right)=d\left(0, x_{n}\right)$ for $n \in \mathbb{N} \cup\{0\}$.

Also, we have

$$
\begin{align*}
d\left(T x_{m}, T x_{n}\right) \leq d\left(0, T x_{m}\right)+d\left(0, T x_{n}\right) & =\alpha d\left(x_{m}, T x_{m}\right)+\alpha d\left(x_{n}, T x_{n}\right) \\
d\left(T 1, T x_{n}\right)-\left(\alpha d(1, T 1)+\alpha d\left(x_{n}, T x_{n}\right)\right) & \leq d(0, T 1)+d\left(0, T x_{n}\right)-\left(\alpha d(1, T 1)+\alpha d\left(x_{n}, T x_{n}\right)\right) \\
& =d(0, T 1)-\alpha d(1, T 1)=\frac{1-2 r^{2}}{1+r} \leq 0 \tag{2.21}
\end{align*}
$$

for $m, n \in \mathbb{N} \cup\{0\}$.

## 3. Generalized Kannan mappings

It is a very natural question of whether or not another fixed-point theorem with $\theta$ exists. In this section, we give a positive answer to this problem.

Theorem 3.1. Define a nonincreasing function $\theta$ as in Theorem 1.1. Let $(X, d)$ be a complete metric space and let $T$ be a mapping on $X$. Suppose that there exists $r \in[0,1)$ such that

$$
\begin{equation*}
\theta(r) d(x, T x) \leq d(x, y) \quad \text { implies } d(T x, T y) \leq r \max \{d(x, T x), d(y, T y)\} \tag{3.1}
\end{equation*}
$$

for all $x, y \in X$. Then $T$ has a unique fixed point $z$ and $\lim _{n} T^{n} x=z$ holds for every $x \in X$.
Proof. Since $\theta(r) d(x, T x) \leq d(x, T x)$, we have, from the assumption,

$$
\begin{equation*}
d\left(T x, T^{2} x\right) \leq r \max \left\{d(x, T x), d\left(T x, T^{2} x\right)\right\} \tag{3.2}
\end{equation*}
$$

and hence

$$
\begin{equation*}
d\left(T x, T^{2} x\right) \leq r d(x, T x) \tag{3.3}
\end{equation*}
$$

for $x \in X$. Let $u \in X$. Put $u_{0}=u$ and $u_{n}=T^{n} u$ for all $n \in \mathbb{N}$. As in the proof of Theorem 2.2, we can prove that $\left\{u_{n}\right\}$ converges to some $z \in X$.

We next show

$$
\begin{equation*}
d(z, T x) \leq r d(x, T x) \quad \text { for all } x \in X \text { with } x \neq z \tag{3.4}
\end{equation*}
$$

Since $u_{n} \rightarrow z$, we have $\theta(r) d\left(u_{n}, T u_{n}\right) \leq d\left(u_{n}, x\right)$ for sufficiently large $n \in \mathbb{N}$. Hence we obtain, from the assumption,

$$
\begin{align*}
d(z, T x) & =\lim _{n \rightarrow \infty} d\left(u_{n+1}, T x\right)=\lim _{n \rightarrow \infty} d\left(T u_{n}, T x\right)  \tag{3.5}\\
& \leq \lim _{n \rightarrow \infty} r \max \left\{d\left(u_{n}, T u_{n}\right), d(x, T x)\right\}=r d(x, T x)
\end{align*}
$$

for $x \in X$ with $x \neq z$.
Let us prove that $z$ is a fixed point of $T$. In the case where $0 \leq r<1 / \sqrt{2}$, we note

$$
\begin{equation*}
\theta(r) \leq \frac{1-r}{r^{2}} \tag{3.6}
\end{equation*}
$$

We will show, by induction,

$$
\begin{equation*}
d\left(T^{n} z, T z\right) \leq r d(z, T z) \tag{3.7}
\end{equation*}
$$

for $n \in \mathbb{N}$ with $n \geq 2$. When $n=2$, (3.7) becomes (3.3), thus (3.7) holds. We assume $d\left(T^{n} z, T z\right) \leq$ $r d(z, T z)$ for some $n \in \mathbb{N}$ with $n \geq 2$. Since

$$
\begin{equation*}
d(z, T z) \leq d\left(z, T^{n} z\right)+d\left(T^{n} z, T z\right) \leq d\left(z, T^{n} z\right)+r d(z, T z), \tag{3.8}
\end{equation*}
$$

we have $d(z, T z) \leq(1 /(1-r)) d\left(z, T^{n} z\right)$, and hence

$$
\begin{align*}
\theta(r) d\left(T^{n} z, T^{n+1} z\right) & \leq \frac{1-r}{r^{2}} d\left(T^{n} z, T^{n+1} z\right) \leq \frac{1-r}{r^{n}} d\left(T^{n} z, T^{n+1} z\right)  \tag{3.9}\\
& \leq(1-r) d(z, T z) \leq d\left(z, T^{n} z\right) .
\end{align*}
$$

Therefore, by the assumption, we have

$$
\begin{equation*}
d\left(T^{n+1} z, T z\right) \leq r \max \left\{d\left(T^{n} z, T^{n+1} z\right), d(z, T z)\right\}=r d(z, T z) . \tag{3.10}
\end{equation*}
$$

By induction, (3.7) holds for $n \in \mathbb{N}$ with $n \geq 2$. Arguing, by contradiction, we assume $T z \neq z$. Then from (3.7), $T^{n} z \neq z$ holds for all $n \in \mathbb{N}$. Then by (3.4), we have

$$
\begin{equation*}
d\left(T^{n+1} z, z\right) \leq r d\left(T^{n} z, T^{n+1} z\right) \leq r^{n+1} d(z, T z) \tag{3.11}
\end{equation*}
$$

This implies $T^{n} z \rightarrow z$, which contradicts (3.7). Therefore, we obtain $T z=z$. In the case where $1 / \sqrt{2} \leq r<1$, as in the proof of Theorem 2.2, we can show that there exists a subsequence $\left\{n_{j}\right\}$ of $\{n\}$ such that $\varphi(r) d\left(u_{n_{j}}, u_{n_{j}+1}\right) \leq d\left(u_{n_{j}}, z\right)$ for $j \in \mathbb{N}$. From the assumption, we have

$$
\begin{equation*}
d(z, T z)=\lim _{j \rightarrow \infty} d\left(u_{n_{j}+1}, T z\right) \leq \lim _{j \rightarrow \infty} r \max \left\{d\left(u_{n_{j}}, u_{n_{j}+1}\right), d(z, T z)\right\}=r d(z, T z) . \tag{3.12}
\end{equation*}
$$

Since $r<1$, the above inequality implies that $T z=z$. Therefore, we have shown that $T z=z$ in both cases.

From (3.4), we obtain that the fixed point $z$ is unique.
Remark 3.2. When the second author was proving Theorem 1.1, he did not feel that $\theta(r)$ was natural. However, since the above proof is easier to understand how $\theta(r)$ works, the authors can faintly feel that $\theta(r)$ is natural.

The following theorem shows that $\theta(r)$ is the best constant for every $r$.
Theorem 3.3. Define a function $\theta$ as in Theorem 1.1. Then for any $r \in[0,1)$, there exist a complete metric space $(X, d)$ and a mapping $T$ on $X$ such that $T$ has no fixed points and

$$
\begin{equation*}
\theta(r) d(x, T x)<d(x, y) \quad \text { implies } d(T x, T y) \leq r \max \{d(x, T x), d(y, T y)\} \tag{3.13}
\end{equation*}
$$

for all $x, y \in X$.
Proof. We have already shown the conclusion in the case where $0 \leq r \leq(1 / 2)(\sqrt{5}-1)$ or $1 / \sqrt{2} \leq$ $r<1$ because $\varphi(r)=\theta(r)$ holds. So let us consider the case where $(1 / 2)(\sqrt{5}-1)<r<1 / \sqrt{2}$. Define a complete subset $X$ of the Euclidean space $\mathbb{R}$ by $X=\left\{x_{n}: n \in \mathbb{N}\right\}$, where $x_{0}=0, x_{1}=1$, $x_{2}=1-r$, and $x_{n}=\left(1-r-r^{2}\right)(-r)^{n-3}$ for $n \geq 3$. Define a mapping $T$ on $X$ by $T x_{n}=x_{n+1}$ for $n \in \mathbb{N}$. Then the following are obvious:
(i) $d\left(T x_{0}, T x_{1}\right)=r=r d\left(x_{0}, T x_{0}\right)=r \max \left\{d\left(x_{0}, T x_{0}\right), d\left(x_{1}, T x_{1}\right)\right\}$,
(ii) $\theta(r) d\left(x_{0}, T x_{0}\right) \geq \theta(r) d\left(x_{2}, T x_{2}\right)=1-r=d\left(x_{0}, x_{2}\right)$,
(iii) $\theta(r) d\left(x_{0}, T x_{0}\right) \geq \theta(r) d\left(x_{n}, T x_{n}\right)=\left(\left(1-r^{2}\right) / r^{2}\right) d\left(x_{0}, x_{n}\right) \geq d\left(x_{0}, x_{n}\right)$ for $n \geq 3$,
(iv) $d\left(T x_{1}, T x_{2}\right)=r^{2}=r d\left(x_{1}, T x_{1}\right)$.

Since

$$
\begin{equation*}
x_{3}<x_{5}<x_{7}<\cdots<x_{0}<\cdots<x_{8}<x_{6}<x_{4}<x_{2}<x_{1} \tag{3.14}
\end{equation*}
$$

we have the following:
(i) $d\left(T x_{1}, T x_{n}\right)<d\left(x_{2}, x_{3}\right)=r^{2}=r d\left(x_{1}, T x_{1}\right)$ for $n \geq 3$,
(ii) $d\left(T x_{2}, T x_{n}\right)-r d\left(x_{2}, T x_{2}\right) \leq d\left(x_{3}, x_{4}\right)-r^{3}=2 r^{2}-1 \leq 0$ for $n \geq 3$,
(iii) $d\left(T x_{m}, T x_{n}\right) \leq d\left(T x_{m}, T x_{m+1}\right)=r d\left(x_{m}, T x_{m}\right)$ for $3 \leq m<n$.

This completes the proof.

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## Call for Papers

As a multidisciplinary field, financial engineering is becoming increasingly important in today's economic and financial world, especially in areas such as portfolio management, asset valuation and prediction, fraud detection, and credit risk management. For example, in a credit risk context, the recently approved Basel II guidelines advise financial institutions to build comprehensible credit risk models in order to optimize their capital allocation policy. Computational methods are being intensively studied and applied to improve the quality of the financial decisions that need to be made. Until now, computational methods and models are central to the analysis of economic and financial decisions.

However, more and more researchers have found that the financial environment is not ruled by mathematical distributions or statistical models. In such situations, some attempts have also been made to develop financial engineering models using intelligent computing approaches. For example, an artificial neural network (ANN) is a nonparametric estimation technique which does not make any distributional assumptions regarding the underlying asset. Instead, ANN approach develops a model using sets of unknown parameters and lets the optimization routine seek the best fitting parameters to obtain the desired results. The main aim of this special issue is not to merely illustrate the superior performance of a new intelligent computational method, but also to demonstrate how it can be used effectively in a financial engineering environment to improve and facilitate financial decision making. In this sense, the submissions should especially address how the results of estimated computational models (e.g., ANN, support vector machines, evolutionary algorithm, and fuzzy models) can be used to develop intelligent, easy-to-use, and/or comprehensible computational systems (e.g., decision support systems, agent-based system, and web-based systems)

This special issue will include (but not be limited to) the following topics:

- Computational methods: artificial intelligence, neural networks, evolutionary algorithms, fuzzy inference, hybrid learning, ensemble learning, cooperative learning, multiagent learning
- Application fields: asset valuation and prediction, asset allocation and portfolio selection, bankruptcy prediction, fraud detection, credit risk management
- Implementation aspects: decision support systems, expert systems, information systems, intelligent agents, web service, monitoring, deployment, implementation

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| Manuscript Due | December 1, 2008 |
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| First Round of Reviews | March 1, 2009 |
| Publication Date | June 1,2009 |

## Guest Editors

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## Mathematical Problems in Engineering

## Special Issue on Short Range Phenomena: Modeling, Computational Aspects, and Applications

## Call for Papers

In recent years, the mathematical formalism of impulsive systems (based on impulsive differential equations) has tried to join together the rigorous aspects from continuous systems formalism and the wide range of applications of discrete systems formalism. They were introduced to handle many evolution processes which are subject to singular short-term perturbations. Abrupt changes must be approached with mathematical and technical aspects dealing with the final evolution of such impulsive sources, whose effects are entirely transferred to the new state of the systems like transitions in quantum mechanics. Modern aspects in physics (quantum theory) and mathematics (wavelets, fractal theory) should be expedient in modeling short range phenomena and describing dynamics of perturbations and transitions in natural systems (advanced materials science) and advanced systems (optic, electronic, and quantum devices).

Thus, a special issue on all theoretical, computational, and practical aspects of modeling short range phenomena would be an opportunity of extending the research field of wavelets analysis, fractal theory, and applied mathematics (signal processing, control theory) for presenting new fundamental aspects in science and engineering. We are soliciting original high-quality research papers on topics of interest connected with modeling short range phenomena that include but are not limited to the following main topics:

- Mathematical aspects of pulse generation
- Dynamical and computational aspects of pulse measurement
- Wavelets analysis of localized space-time phenomena
- Stochastic aspects of pulses, sequences of pulses and time series

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